
Orna Agmon Ben-Yehuda

Presents

Communication-Efficient Online Detection of Network-Wide Anomalies

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Coming on Spring 2011 to a

Seminar 236803 on Processing and Mining Distributed Data

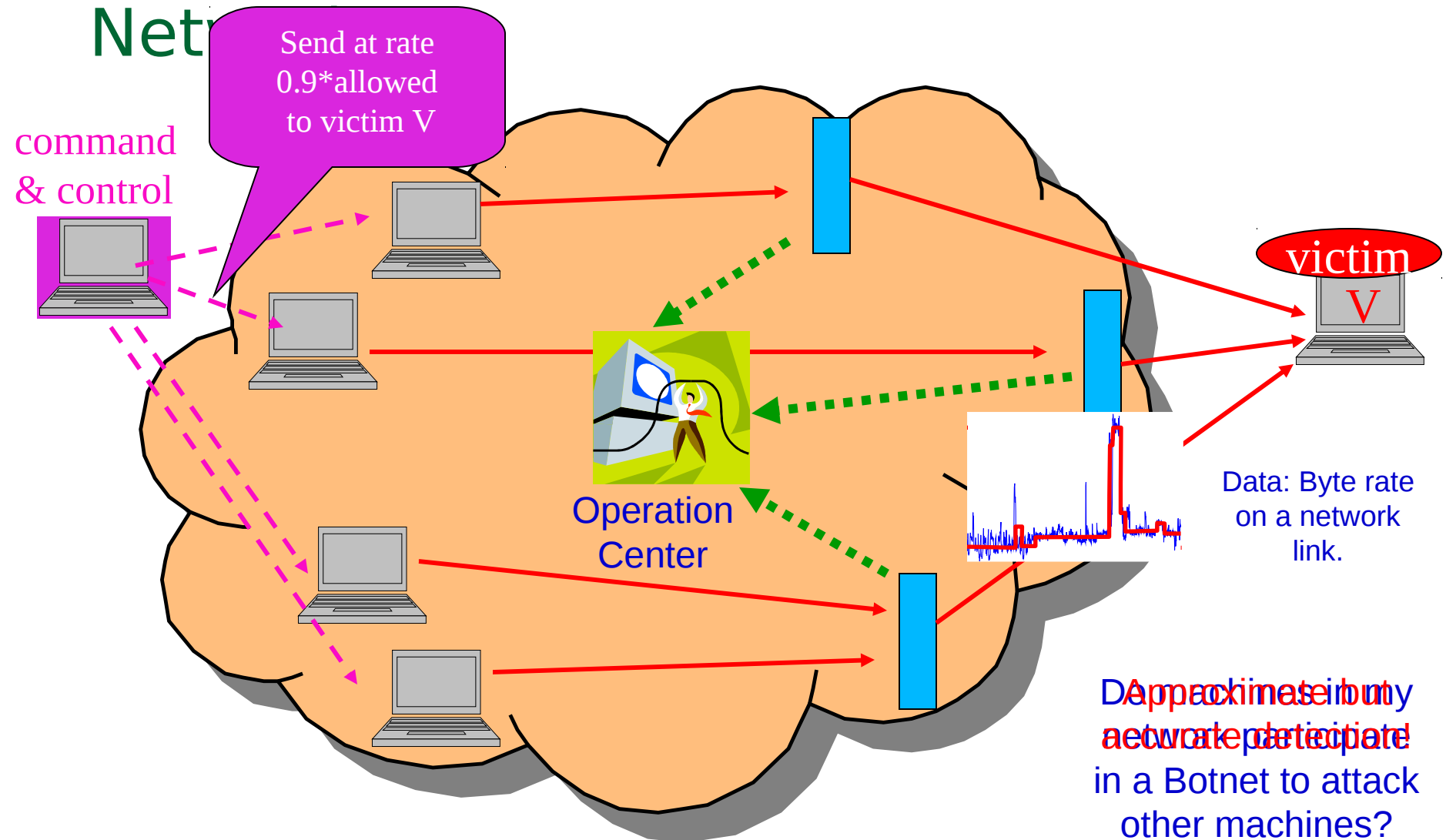
Near you

Network-Wide Anomalies

- Are bad:
 - Router mis-configurations
 - Border Gateway Protocol (BGP) policy modifications
 - Device failures
- Or even malicious:
 - DDOS attacks
 - Viruses, spam sending
 - Port scanning
- But also just unpredictable
 - Flash Crowds (mob) supercomputing



Detection Problems in Enterprise Networks



For efficient and scalable detection, push data processing to the edge of network!

We shall talk about:

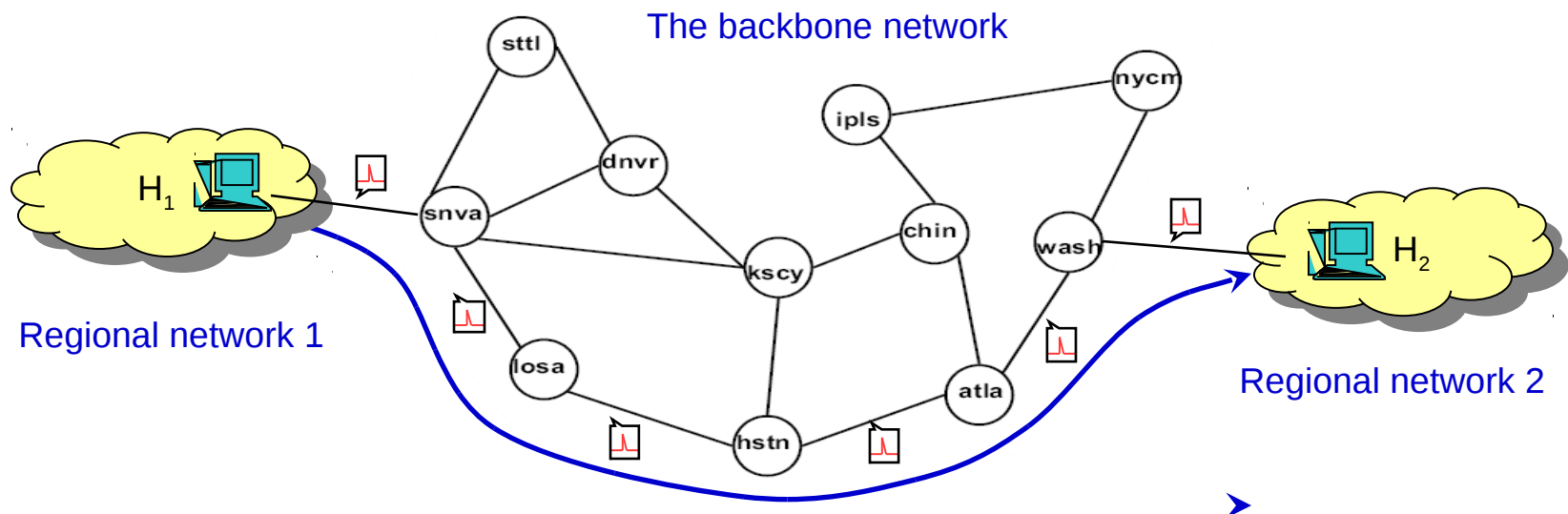
- Lakhina et al.'s centralized algorithm
- Decentralized anomaly detection
- Slack determination
- Evaluation
- Open Discussion

Towards Decentralized Detection

- Lakhina et al.: Distributed Monitoring & Centralized Computation
 - Stream-based data collection
 - *Periodically* evaluate detection function over collected data
 - Doesn't scale well in network size, timescale, detection delay
- Huang et al.: Decentralized Detection
 - *Continuously* evaluate detection function in a decentr. way
 - Low-overhead, rapid response, accurate and scalable
 - Detection accuracy controllable by a “tuning knob”
 - Provable guarantee on detection error (false alarm rate)
 - Flexible tradeoff between overhead and accuracy

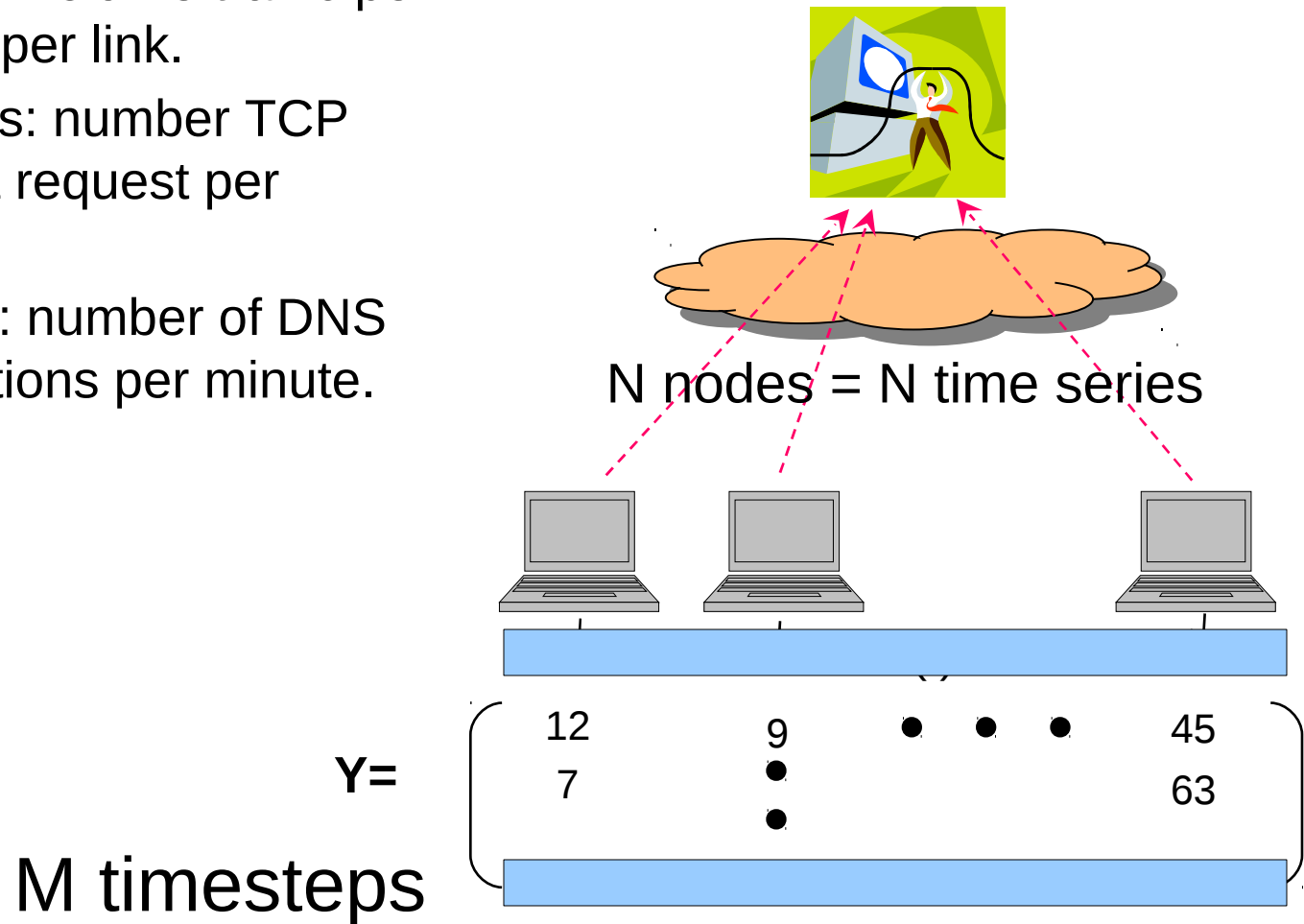
Detection of Network-wide Anomalies

- A **volume anomaly** is a sudden change in an **Origin-Destination flow** (i.e., point to point traffic)
- Given **link** traffic measurements, **detect** the volume anomalies

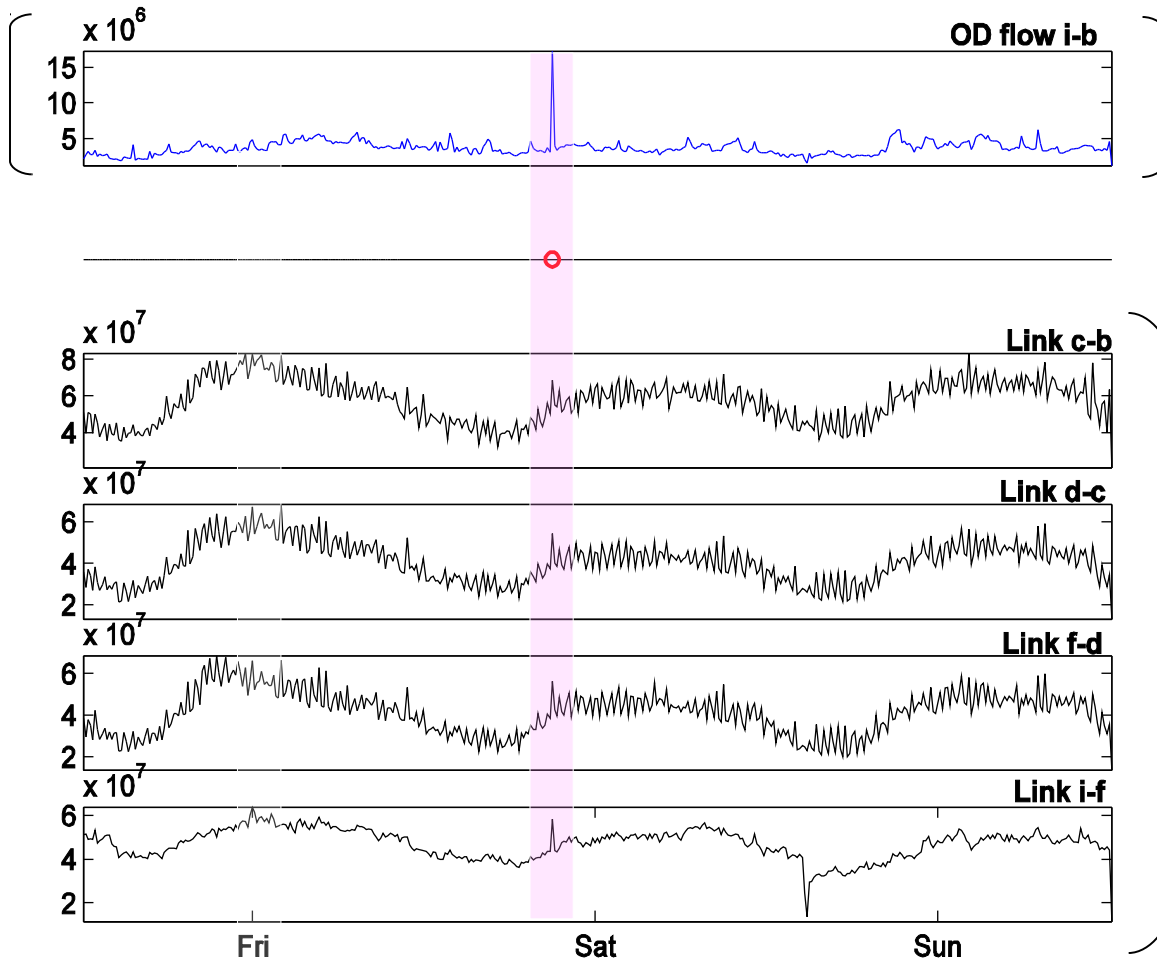


The Data Collected by Monitors

- Routers: volume traffic per second per link.
- Firewalls: number TCP connect request per second.
- Servers: number of DNS transactions per minute.



Flow vs. Link (Lakhina et al.)

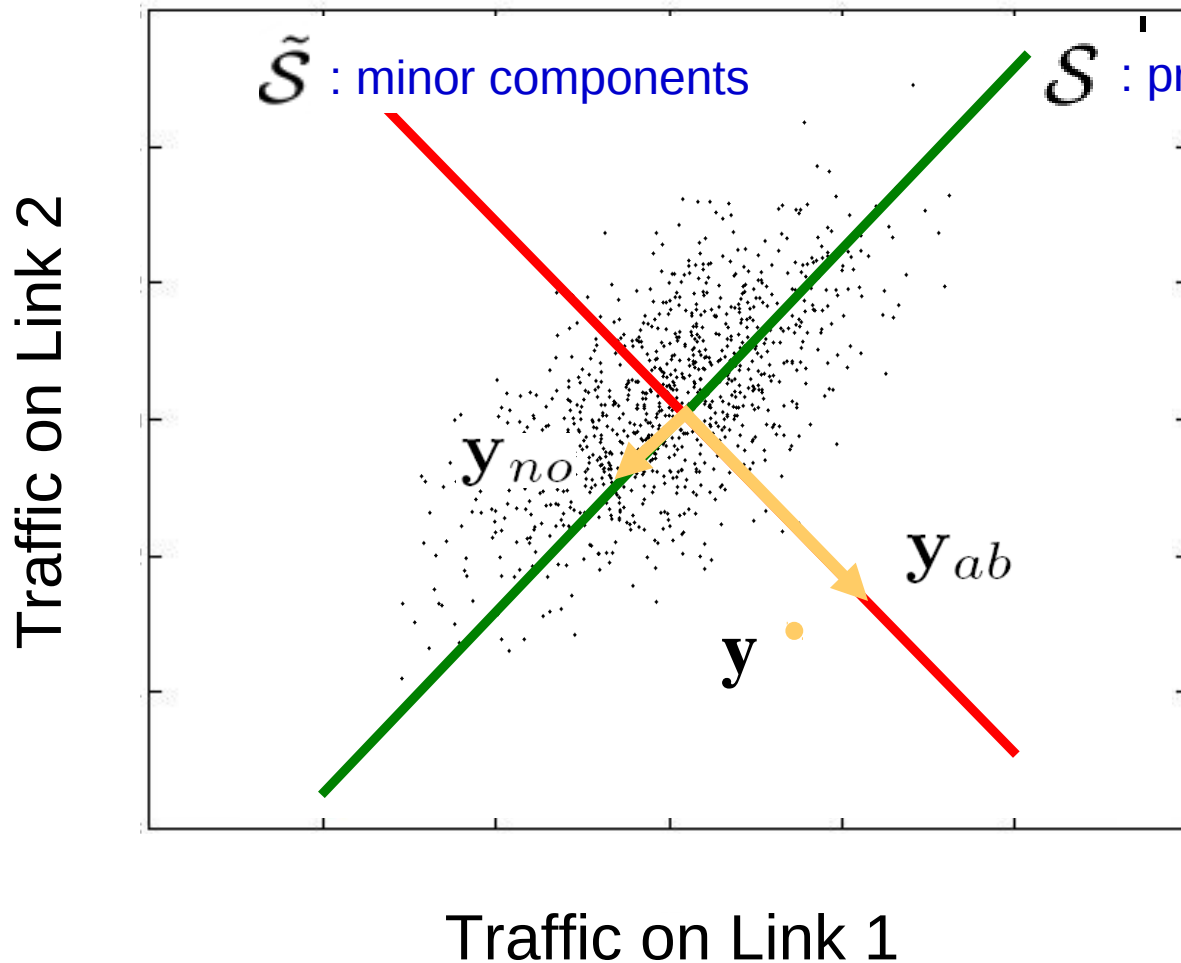


Anomalies in (unobserved) flow data

Observed network link data = aggregate of application-level flows
Each link is a dimension

Finding anomalies in high-dimensional, noisy data is difficult!

Principal Component Analysis (PCA)



\tilde{S} : minor components

S : principal components
Principal components are top eigenvectors of covariance matrix.

$$Y Y^T$$

They are also directions of maximal variance.

They form the subspace projection matrices C_{no} and C_{ab}

$$y_{no} = C_{no}y$$

$$y_{ab} = C_{ab}y$$

Anomalous traffic usually results in a large value of y_{ab}

The Subspace Method (Lakhina'04)

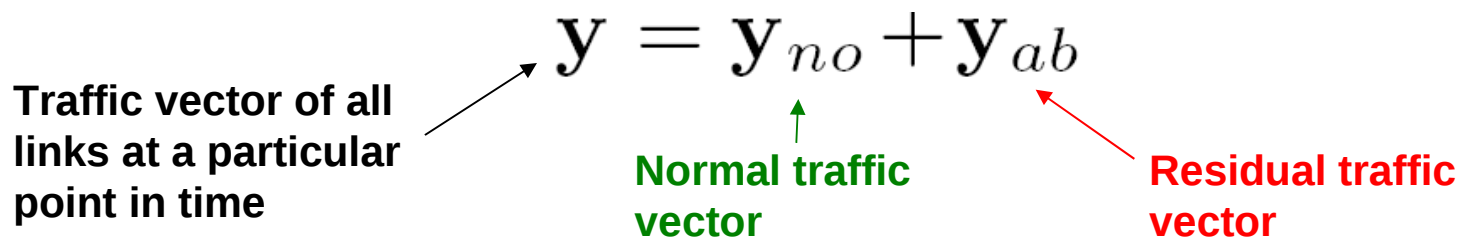
- An approach to separate normal from anomalous traffic based on Principal Component Analysis (PCA)
- **Normal Subspace** \mathcal{S} : space spanned by the top k principal components
- **Anomalous Subspace** $\tilde{\mathcal{S}}$: space spanned by the remaining components
- Then, decompose traffic on all links by **projecting** onto \mathcal{S} and $\tilde{\mathcal{S}}$ to obtain:

$$\mathbf{y} = \mathbf{y}_{no} + \mathbf{y}_{ab}$$

Traffic vector of all links at a particular point in time

Normal traffic vector

Residual traffic vector



Link Traffic Variance of Principle Components

- Link matrices have low dimensionality

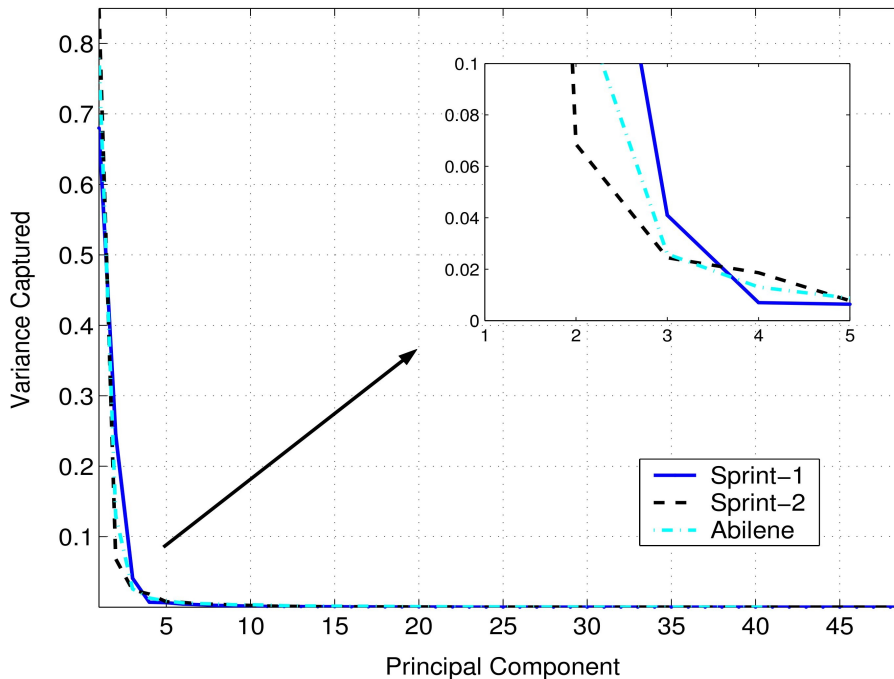


Figure 2: Fraction of total link traffic variance captured by each principal component.

Projections onto Principle Components – normal and abnormal traffic variation

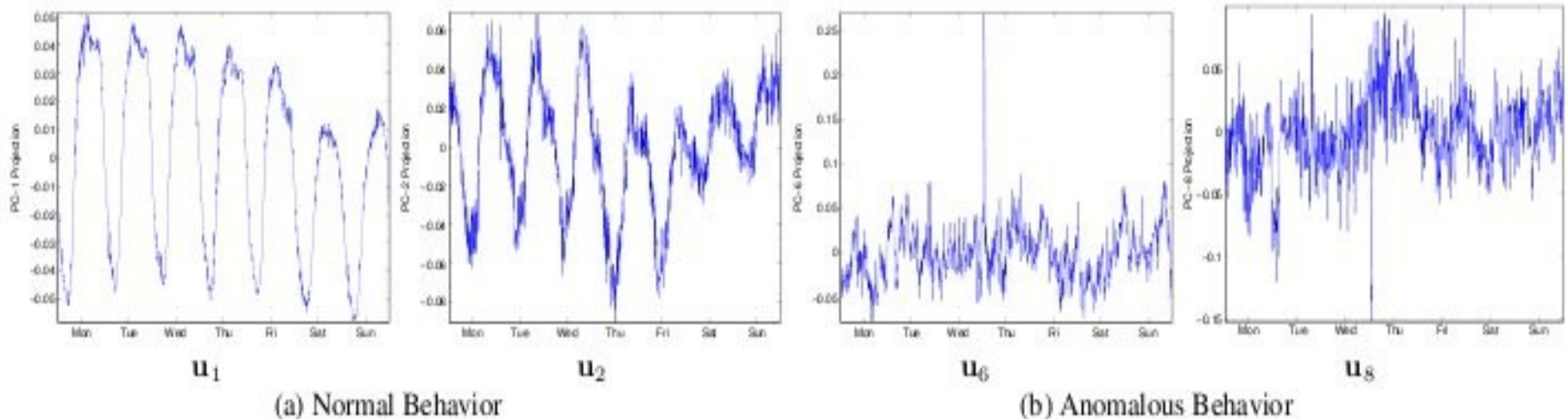
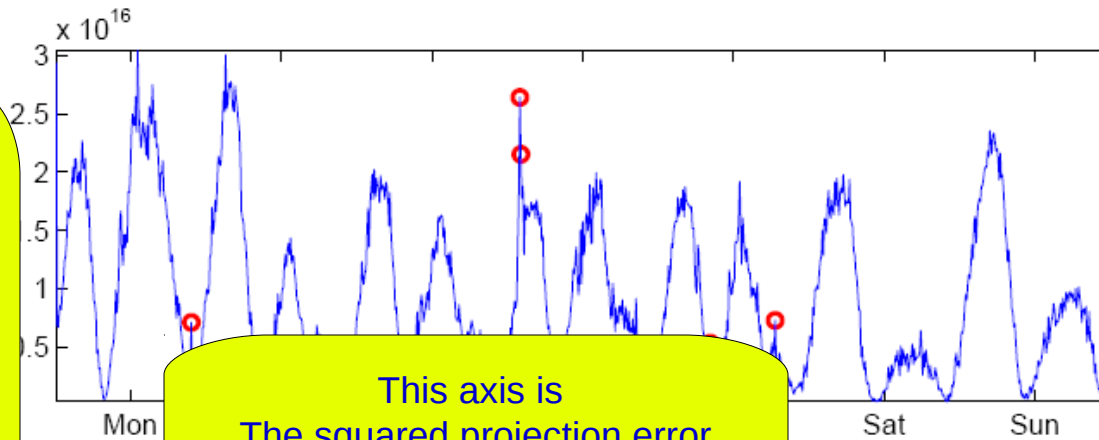


Figure 3: Projections onto principal components showing normal and anomalous traffic variation.

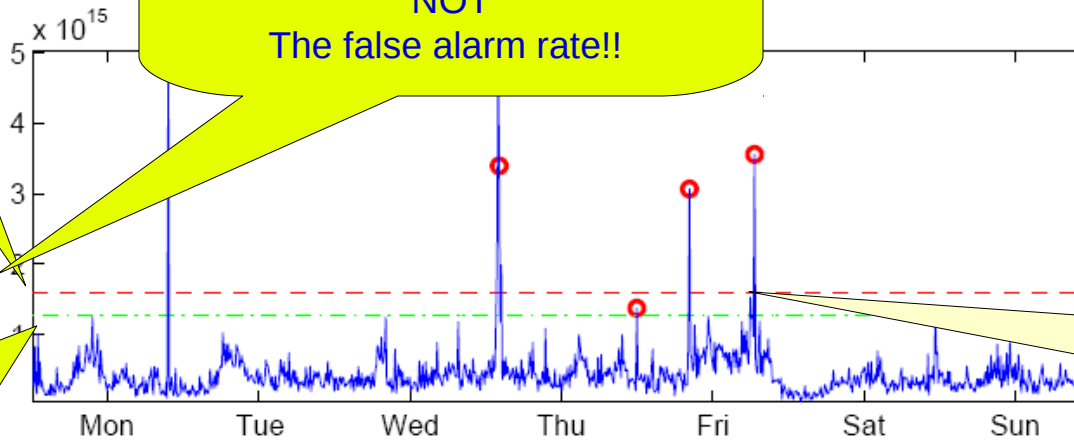
Detection Illustration



Value of $\|y\|^2$
over time
(all traffic)

$1-\alpha=99.9$
99.9% of
Alarms
Are Real,
But
More
Anomalies
Go
undetected

This axis is
The squared projection error
NOT
The false alarm rate!!



Value of $\|C_{ab}y\|^2$
over time

This small spike
is not an anomaly
we wished to detect

Red dots: anomalies

Blue curve: traffic data

$1-\alpha=99.5$
Only
99.5% of
Alarms
Are real
But many
Anomalies
Are
detected

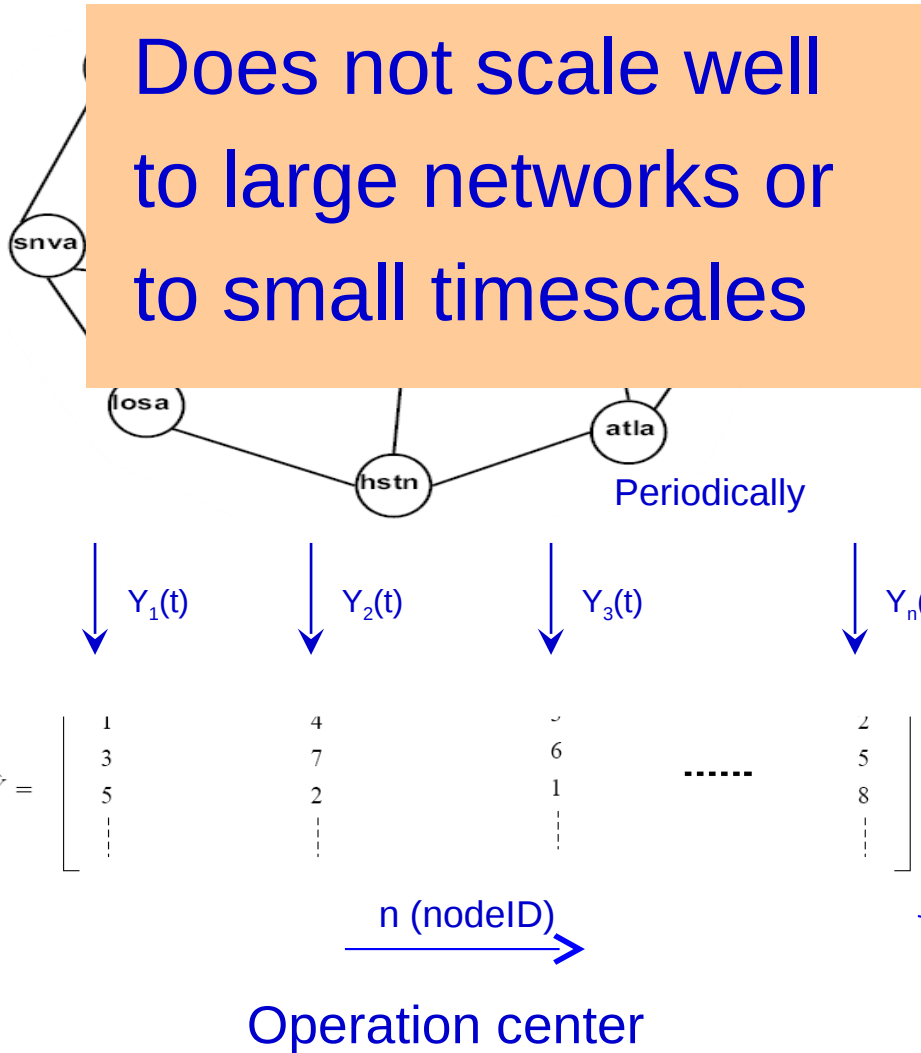
Detection Threshold

$$\|C_{ab} y\|^2 > Q_\alpha$$

- Q_α is a threshold on the Squared Projection Error (SPE). It guarantees a false alarm rate of less than α .
- Jackson & Mudholkar: **computed threshold based on the abnormal eigenvalues of the covariance matrix.**
 - No matter where the distinction is made (how many components are considered normal).
 - No matter what the mean amount of traffic is.
 - For multivariate Gaussian distribution only.
- Jensen & Solomon: In practice, holds for different distributions.
- Lakhina et al. Believe traffic is multivariate Gaussian.
 - but have not verified this.

The Centralized Algorithm

Does not scale well to large networks or to small timescales



- Data matrix Dat

- 1) Each link produces a column of m data over time.
- 2) n links produce a row data y at each time instance.

Detection by Squared Prediction Error (SPE):

$$\|C_{ab} y\|^2 > Q_\alpha$$

Projection

Threshold

C_{ab}

Q_α

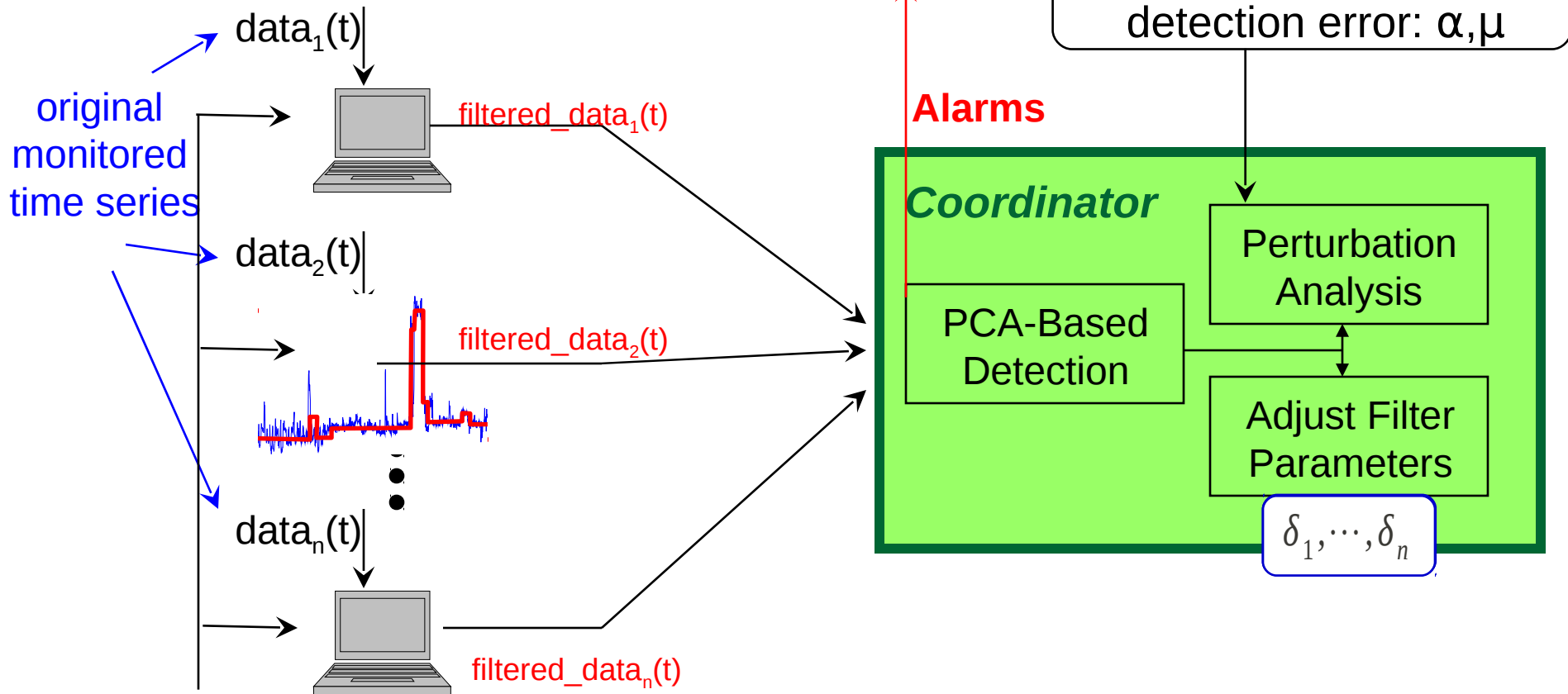
Eigen vectors

Eigen values

PCA on Y

Huang et al.: In-Network Detection Framework

Distr. Monitors



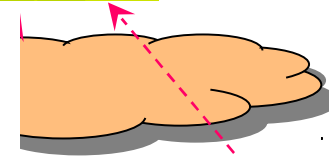
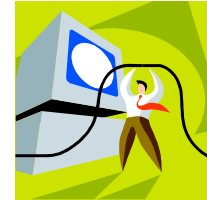
The Communication and Error Tradeoff

Approximate Info.

← PCA on \hat{Y}

← \hat{Y}

$$\|\hat{C}_{ab} \hat{y}\|^2 > \hat{Q}_\alpha$$



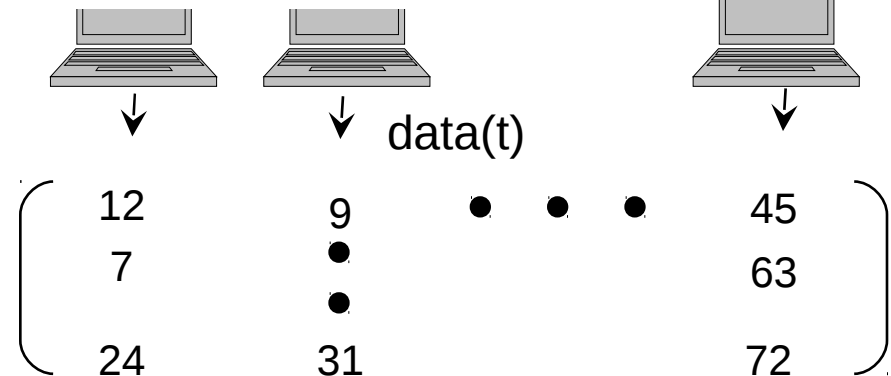
tered_data(t)

The bigger the filtering parameter δ_i ,
the less the communication overhead,
but the more the detection error!

$$\|C_{ab} y\|^2 > Q_\alpha$$

← PCA on Y

$Y =$



The coordinator computes a set of good $\delta_1, \dots, \delta_n$ to manage this difference.

The Protocol At Monitors

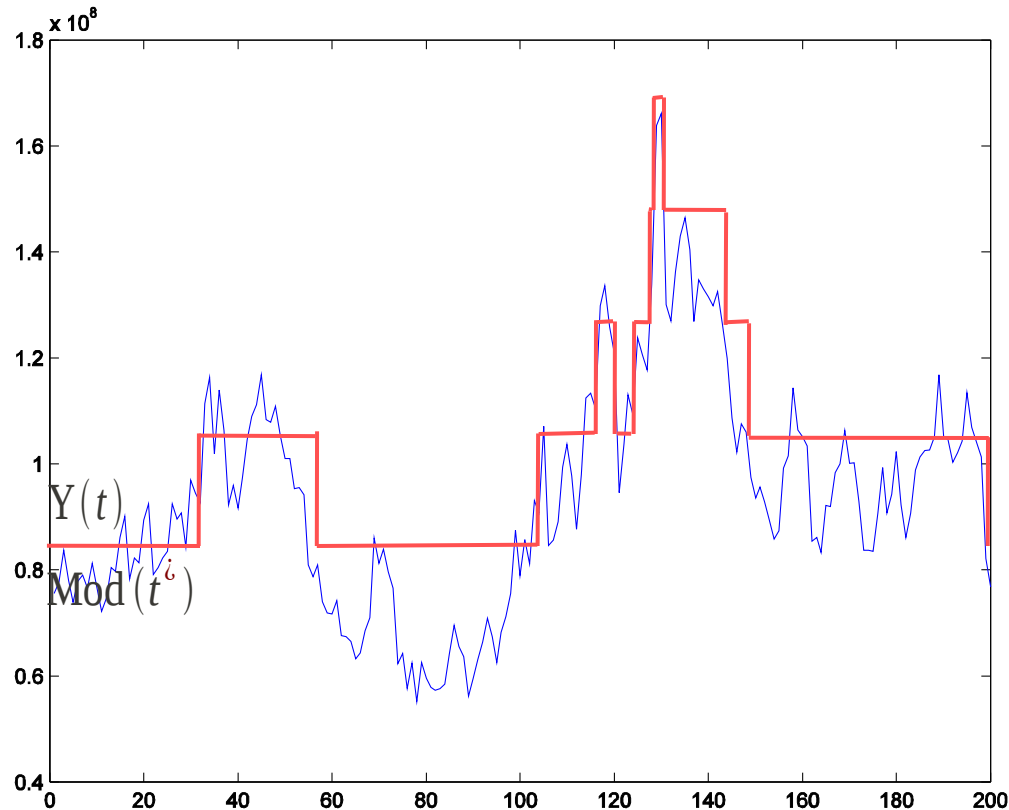
- Monitor i updates information if

$$|Y_i(t) - \text{Mod}_i(t^i)| > \delta_i$$

$\delta_1, \dots, \delta_n$ are the *filtering parameters*

- $\text{Mod}_i(t^i)$ can be based on any prediction **model** built on historical data.
 - The prediction model is known to both monitor and coordinator.
 - For example, the average of last 5 communicated signal values.

The Protocol At Monitors



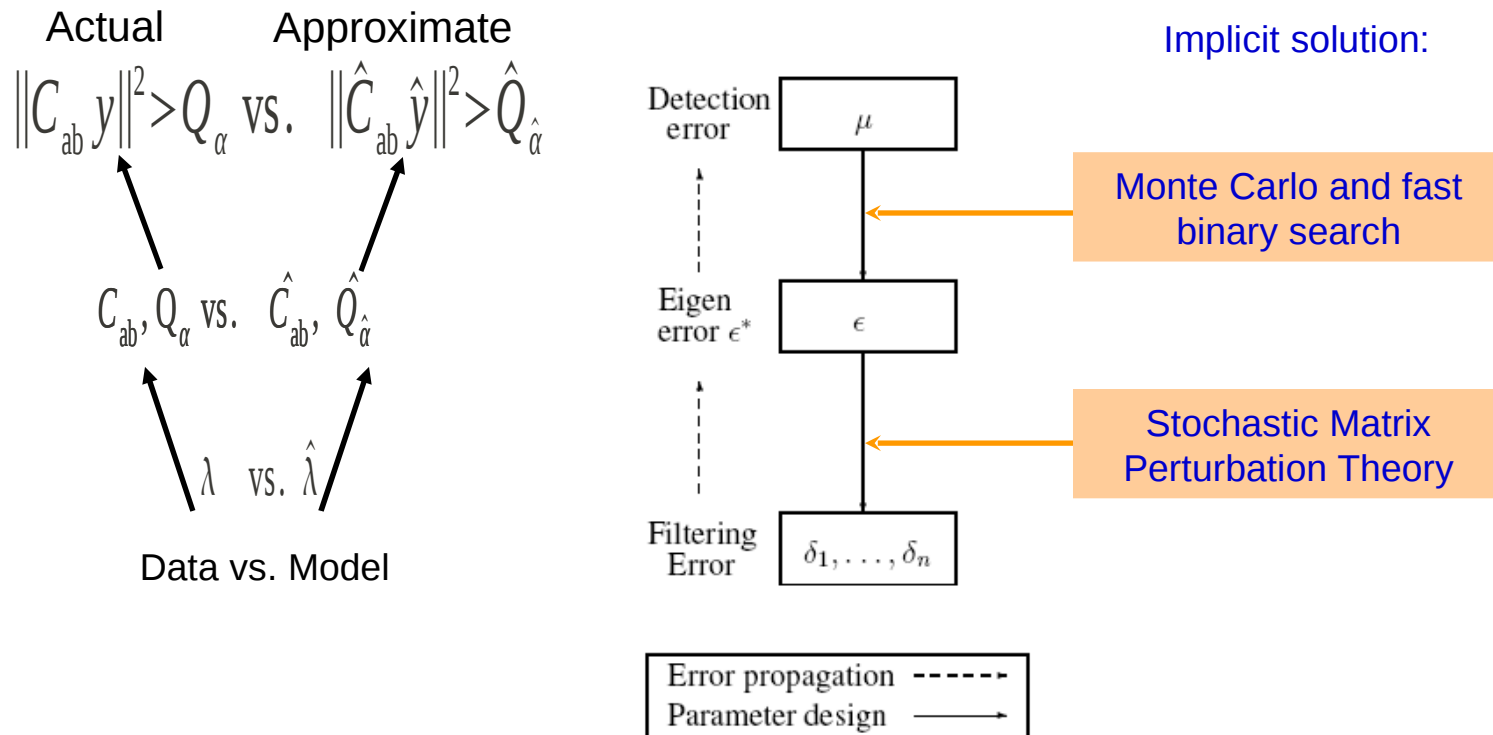
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- Simple but enough to achieve 10x data reduction

The Protocol at the Coordinator

- Create **new time data** from communication and predictions
- **Update (cyclic) matrix**: add new data, lose oldest
- Re-compute **PCA** (residual projection matrix, threshold)
- **Detect** anomalies, **fire** warnings
- Update **slacks** when needed (no details...)

Parameter Design and Error Control

- Users specify an upper bound on **false alarm rate**, then we determine the filtering parameters δ 's

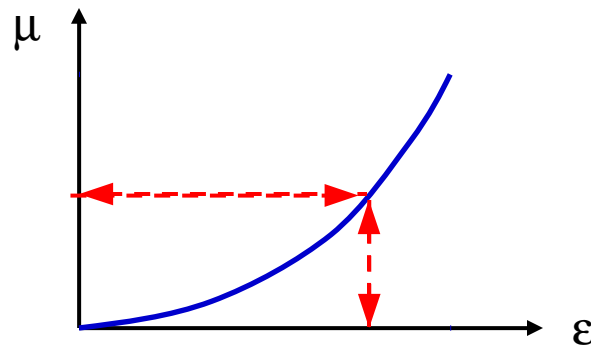


Eigen error: L_2 norm of the difference between

the approximate eigenvalues and the actual ones

Parameter Design and Error Control (II)

- Detection Error $\mu \rightarrow$ Eigen-Error ε
 - Monte Carlo simulation to find the mapping from ε to μ



- For the given μ , a fast binary search to find an ε

From Eigen-Error to detection Deviation

$$\Pr \left[\|\mathbf{C}_a \mathbf{y}\|^2 > Q_\alpha \right] = \Pr \left[X > c_\alpha \right] = \alpha,$$

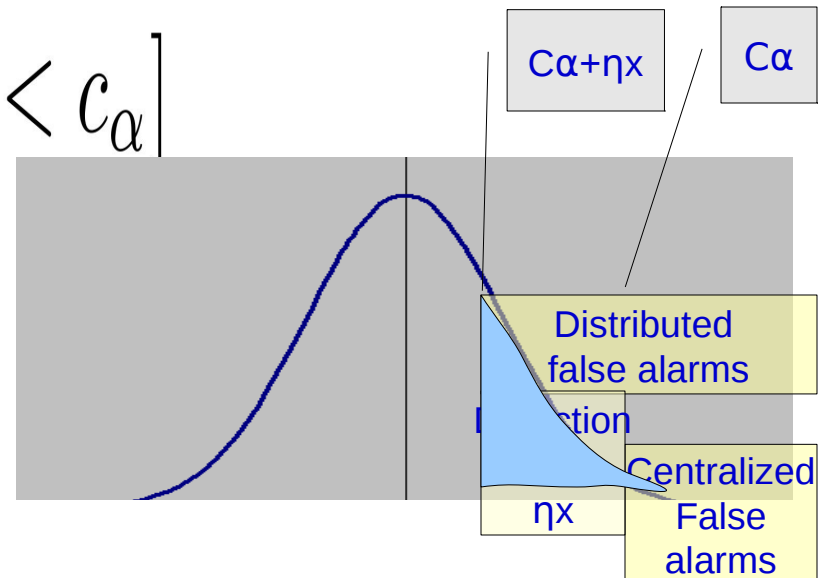
Normalized form of
 $\|\mathbf{C}_{ab} \mathbf{y}\|^2$
 (Jensen & Solomon)

(1- α)-th percentile

$$\mu = \Pr \left[c_\alpha - \eta_X < N(0, 1) < c_\alpha \right]$$

Upper bound on
 $|\hat{X} - X|$

Estimated using max of
 Monte Carlo results



Parameter Design and Error Control (III)

Eigen-Error $\varepsilon \rightarrow$ Filtering parameters δs

- Error Matrix: $W = Y - \hat{Y}$
- Elements of column vector W_i bound by δ_i
- Assumptions:
 - W_i are independent, radially symmetric random vectors
 - For each i , all elements of a column vector are i.i.d random variables with mean 0 and variance σ^2
- The variance σ^2 is a function of the slacks δ_i

Parameter Design and Error Control (III)

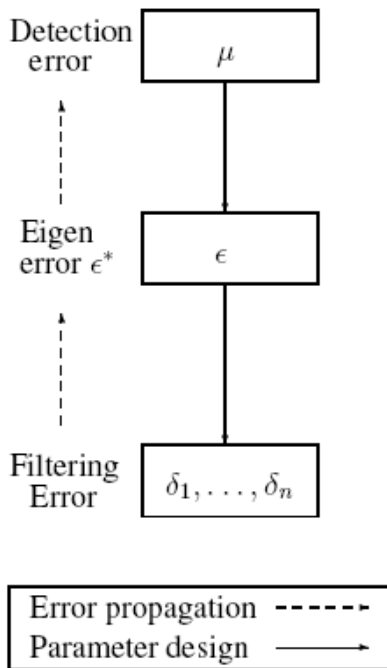
Theorem: Setting δ_i to satisfy:

Average of
Perturbed
eigenvalues

$$2\sqrt{\frac{\bar{\lambda}}{m} \cdot \sum_{i=1}^n \sigma_i^2} + \sqrt{\left(\frac{1}{m} + \frac{1}{n}\right) \sum_{i=1}^n \sigma_i^4} = \epsilon$$

Tolerable
Eigen-Error

Guarantees $\epsilon^i < \epsilon$ with high probability.



Absent:
 A connection between
 local variances and
 local slacks



Slack Allocation Methods

1. **Homogeneous** slack allocation: **uniform distribution** of errors in range $[-\delta_i, \delta_i]$

- $\sigma_i = \frac{\delta_i^2}{3}$, results in closed expression for δ

2. **Homogeneous** slack allocation: **local variance estimation**

- $\sigma_i = \sigma_i(\delta)$, monitors approximate locally by fitting an (e.g., quadratic) function according to a recent window of data. Approximation sent to coordinator.

3. **Heterogeneous** slack allocation.

- Assume **uniform distribution** of errors in range
- Minimize communication; Solve using Lagrange multipliers.

Evaluation: Accuracy and Cost

- Given user-specified false alarm rate, evaluate the actual detection accuracy and communication overhead
- Experiment setup
 - Abilene backbone network data of one week:
 - 121 flows, 41 links, 1008 10 minute periods
 - Traffic matrices of size 1008 X 41
 - Set uniform slack $\delta_i = \delta$ for all monitors
 - Injected: 60 small “bursts” +60 large “anomalies”
 - Threshold corresponding 0.5% false alarm rate
 - **How many experiments (repetitions)?**

Evaluation Metrics

- False alarm rate = false alarms/ bursts
- Missed detection rate = missed detections/anomalies
- Cost = $\text{num}/(n*m)$ = messages per monitor per sampled time points
 - num = all exchanged messages
 - n = number of monitors
 - M = number of time series points

Evaluation Results

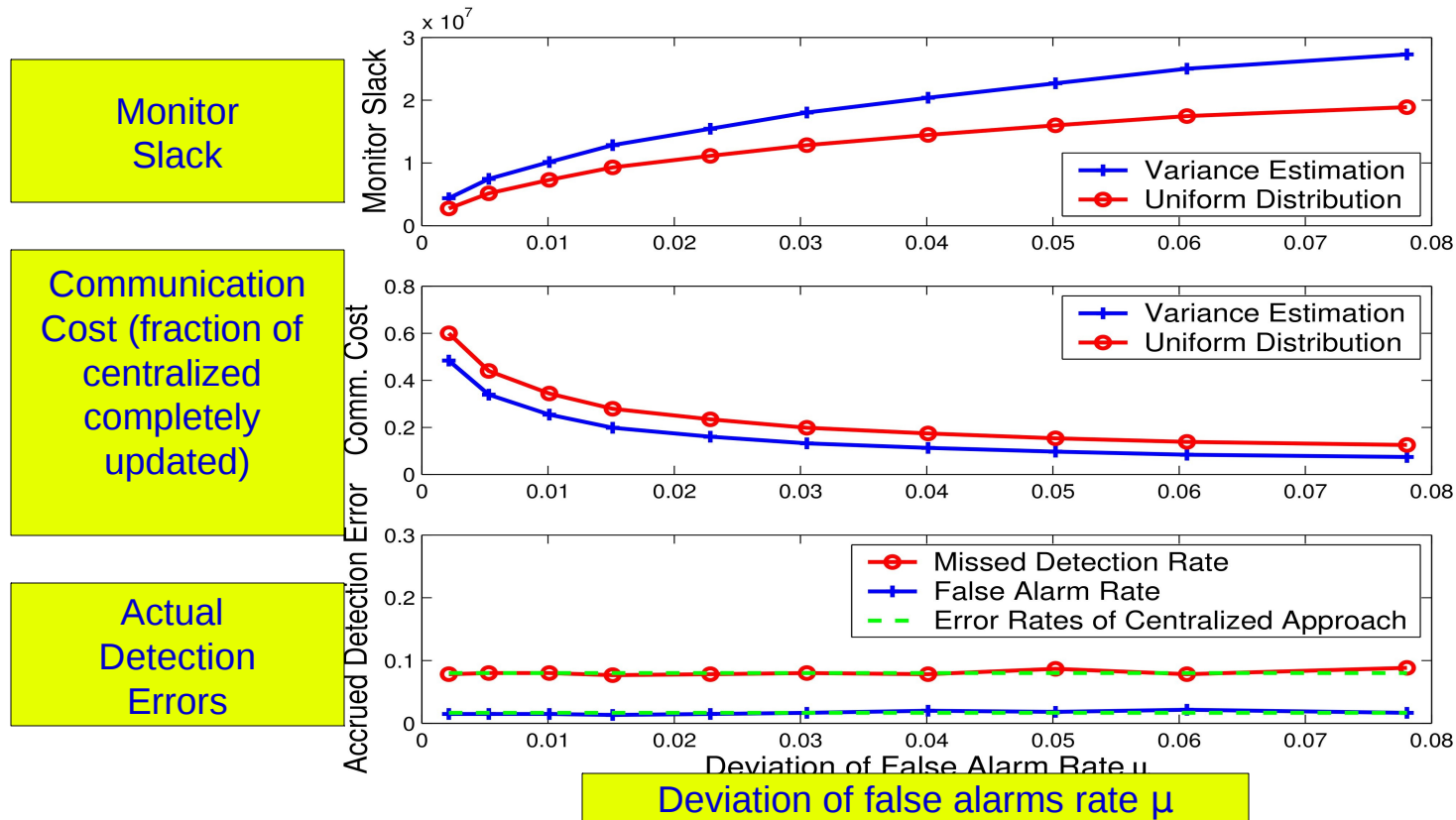
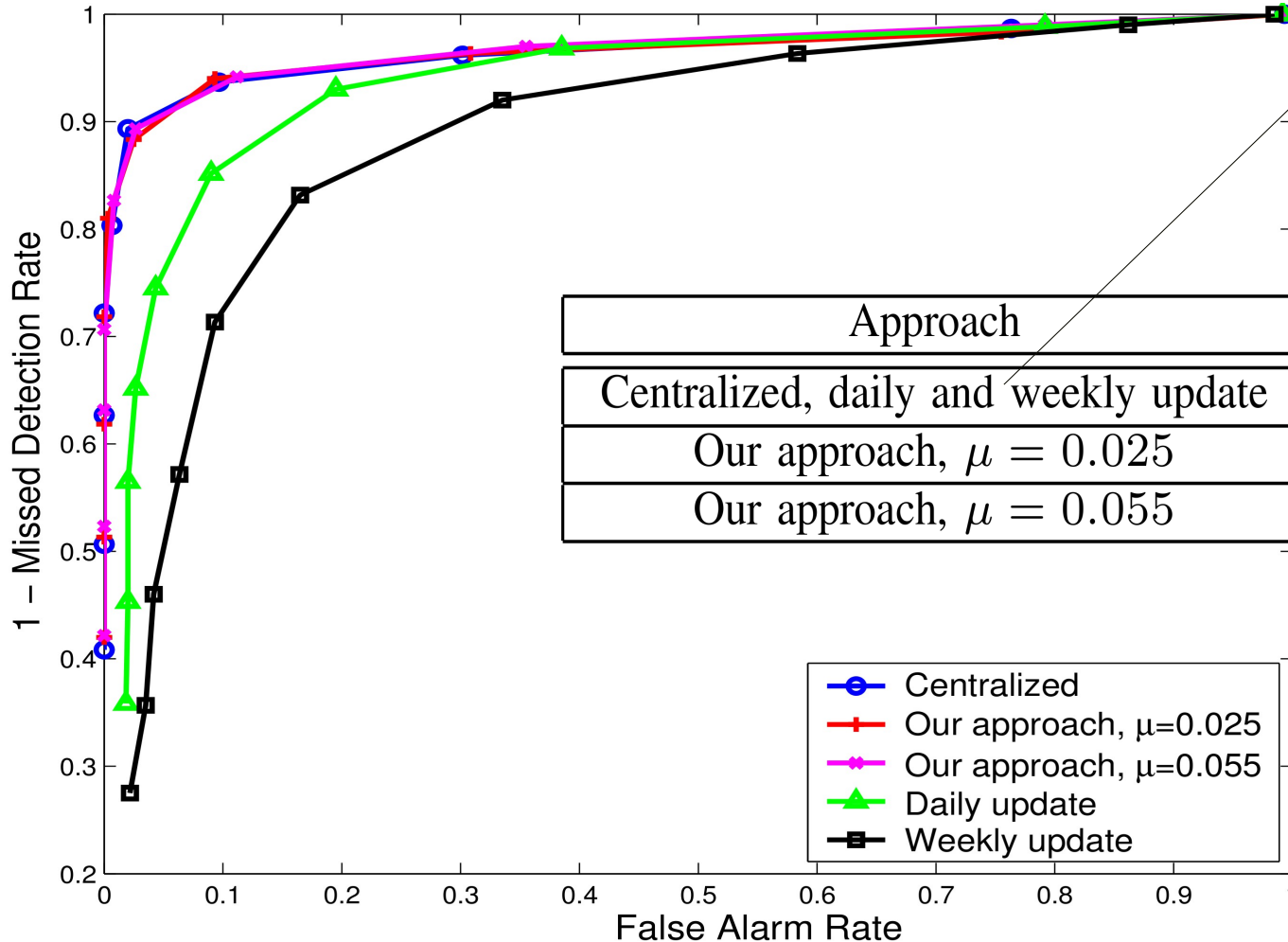


Fig. 6. Monitor slacks, communication cost and accrued detection. The dashed line is the detection error of centralized approach with complete data.

Observations

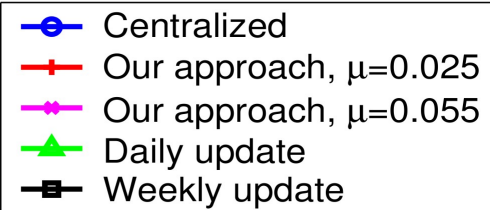
- Homogenous variance estimation outperforms Homogenous Uniform, but not by much (5%-10%).
- Homogenous Uniform method is simple.
- Homogenous Uniform might be “good enough”.
- 80%-90% of the transferred data can be saved without hurting performance.

ROC - Receiver Operating Characteristic Curve



Update rate
Of PCA
(data is always full)

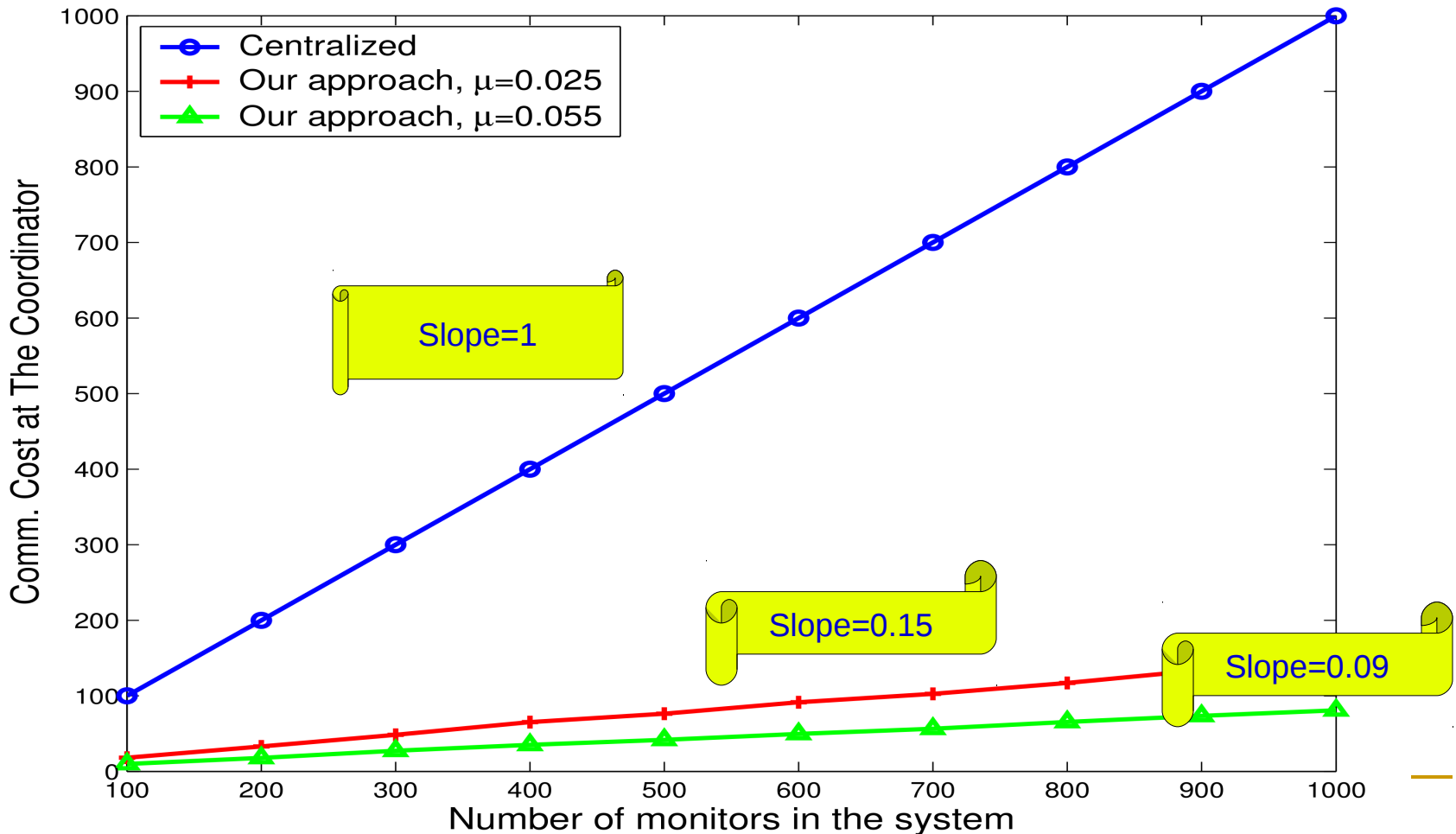
Approach	Communication Cost
Centralized, daily and weekly update	1.000
Our approach, $\mu = 0.025$	0.159
Our approach, $\mu = 0.055$	0.097



Evaluation of Scalability

- BRITE topology generator
- 100-1000 links
- Up to 500*500 Origin-Destination flows
- 4 weeks of realistic data, based of statistical characteristics of Abilene
- In each experiment on n nodes: 5 repetitions, on n randomly picked nodes.

Graceful Scalability by number of monitors: coordinator communication



Summary

- A communication-efficient framework that
 - detects anomalies at desired accuracy level
 - with minimal communication cost
- A distributed protocol for data processing
 - Local monitors decide when to update data to coordinator
 - Coordinator makes global decision and feedback to monitors
- An algorithmic framework to guide the tradeoff between communication overhead and detection accuracy

Discussion



References

[Huang'07] *Communication-Efficient Online Detection of Network-Wide Anomalies*. L. Huang, X. Nguyen, M. Garofalakis, J. Hellerstein, M. Jordan, A. Joseph and N. Taft. To appear in INFOCOM'07.

[Lakhina'04] *Diagnosing Network-Wide Traffic Anomalies*. A. Lakhina, M. Crovella and C. Diot. In SIGCOMM '04.

[Jensen & Solomon] *A Gaussian approximation for the distribution of definite quadratic forms*. D.R. Jensen and H. Solomon, In J. Amer. Stat. Assoc., 67:898-902 (1972).

[Jackson & Mudholkar] *Control Procedures for Residuals Associated with Principal Component Analysis*. J. E. Jackson and G. S. Mudholkar, Technometrics, pages 341–349, 1979.

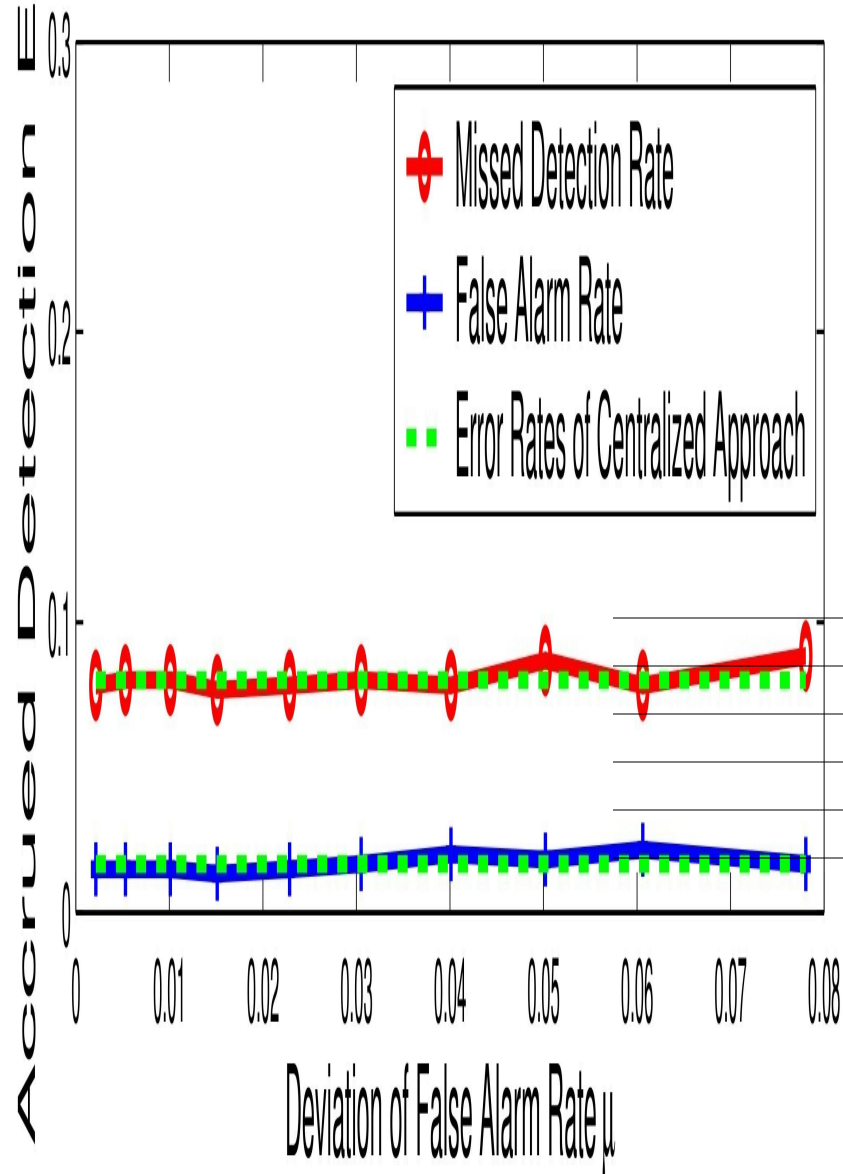
Weaknesses (My Opinion)

- Symmetry + Independence
- Experiments

symmetry + independence

- Is the symmetry + independence assumption valid?
- Correlation may result from simultaneous errors upon surprising data changes, or from (cyclic?) bursts induced by the updating algorithm.

Experiments



Single Experiment
Quantization error:
 $1/60=0.016$
(means one alarm)

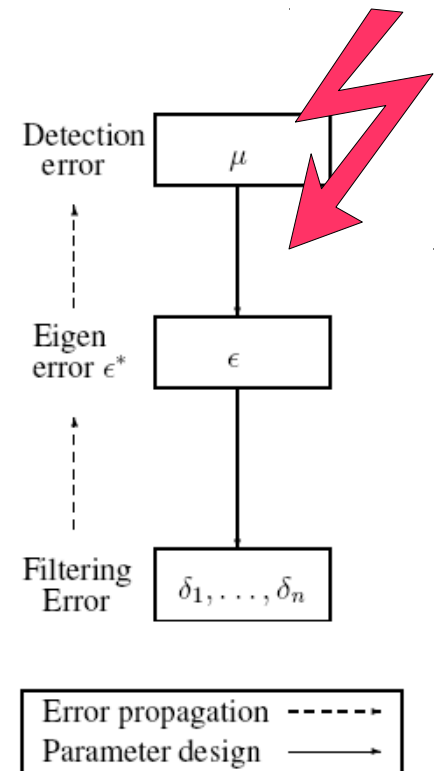
Experiments: Lack of Trend

Experiments do not show a statistically significant trend (dependency) of “tolerated deviation from false alarm rate” and actual false alarm rate.

Estimations are too loose, or

Experiments are too synthetic

Between the lines: user is expected to trust experiment results.



My Summary

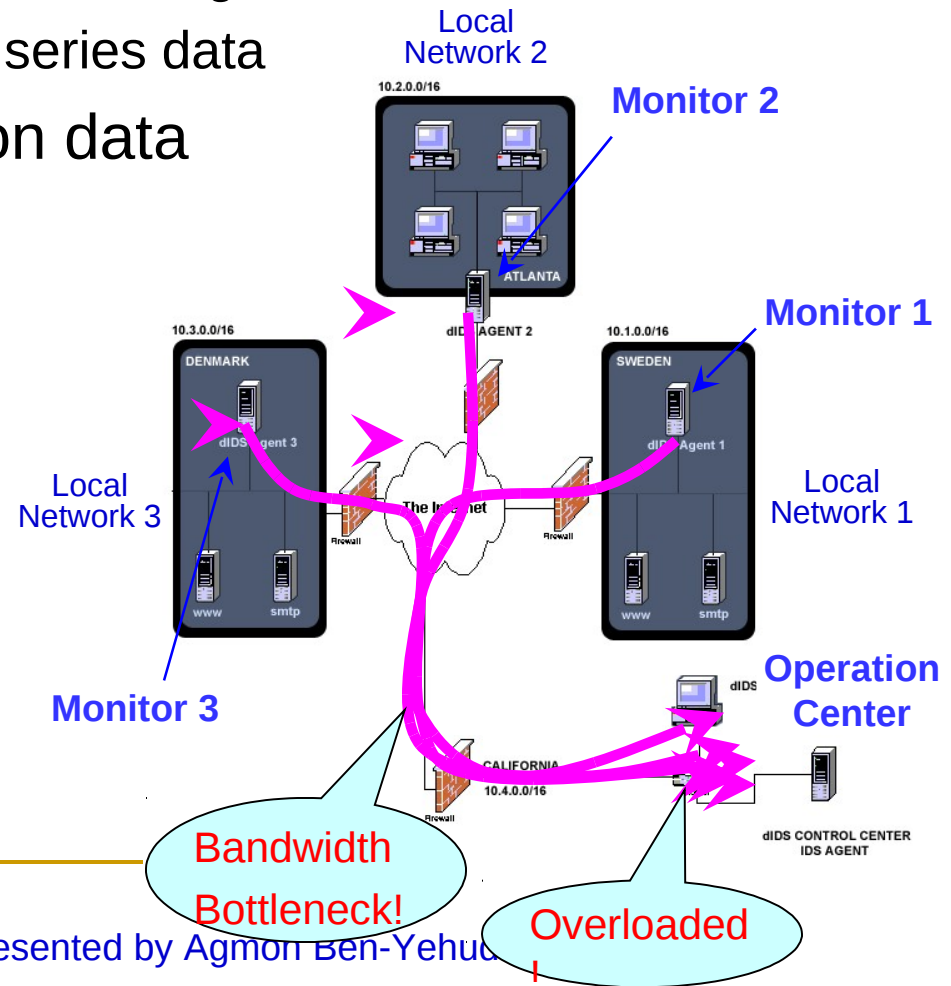
- The decentralized algorithm works well in practice according to insufficient experiments.
- The tuning knob was not proved to work in experiments (to be connected to practical accuracy guarantees).
- Noisier experiments are needed.

Slides

Backup

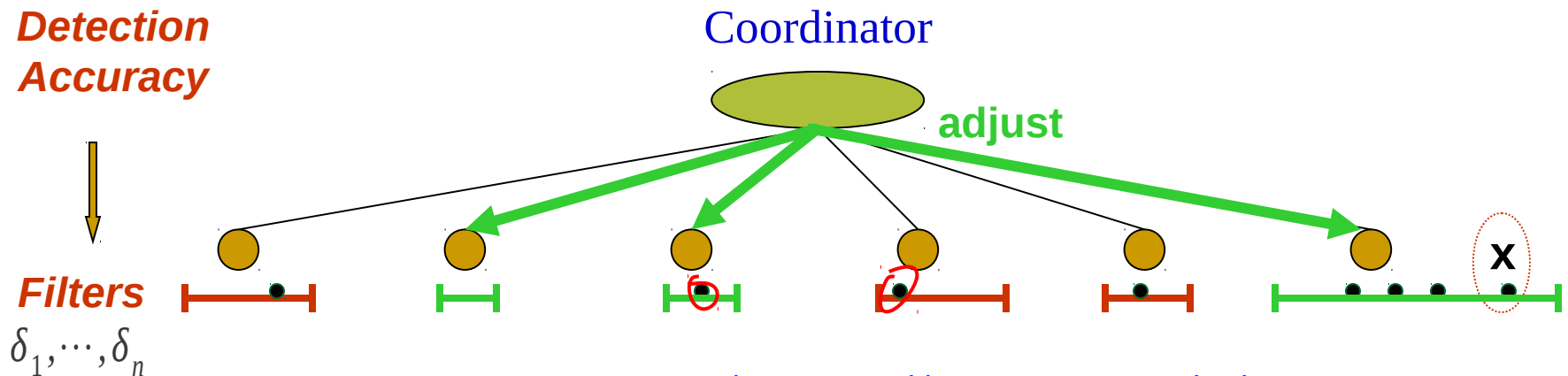
Traditional Distributed Monitoring

- Large-scale network monitoring and detection systems
 - Distributed and collaborative monitoring boxes
 - Continuously generating time series data
- Existing research focuses on data streaming
 - *Centrally* collect, store and aggregate network state
 - Well suited to answering approximate queries and continuously recording system state
 - Incur high overhead!



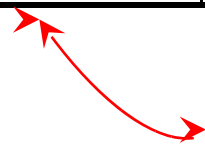
Our Distributed Processing Approach

- A coordinator
 - Is aggregation, correlation and detection center
- A set of distributed monitors
 - Each produces a time series signals
 - Processes data locally, only sends needed info. to coordinator
 - No communication among monitors
 - *Coordinator tells monitors the level of accuracy for signal updates*



Performance

μ	Missed Detections		False Alarms		Data Reduction	
	Week 1	Week 2	Week 1	Week 2	Week 1	Week 2
0.01	0	0	0	0	75%	70%
0.03	0	1	1	0	82%	76%
0.06	0	1	0	0	90%	79%

 error tolerance = upper bound on error

Data Used: Abilene traffic matrix, 2 weeks, 41 links.